

# Application of an Intelligent Control on Economics Dynamic System Described by Differential Algebraic Equation as a New Management Strategy

Raymundo Juarez-Del-Toro, Carmen B. Salcido, Sandra Lopez  
Facultad de Contaduría y Administración, unidad Torreón, Universidad Autónoma de Coahuila

r.juarez@uadec.edu.mx, carmen.borrego.salcido@hotmail.com,  
salopezc@uadec.edu.mx

José Roberto Cantú-González  
Escuela de Sistemas PMRV, unidad Acuña, Universidad Autónoma de Coahuila  
roberto.cantu@uadec.edu.mx

## Abstract

In this paper, we explore the application of the robust control approach of Attractive Ellipsoid Methodology on a class of dynamic system described by Differential Algebraic Equations (DAE) in economics under the effect of bounded external disturbances. To achieve a specific economic goal we will design an integral management strategy which allows to minimize the size of the invariant attractive ellipsoid, associated with the dynamic system, with a good performance in the rejection of external disturbances. The right-hand side of DAE belongs to the given *Quasi-Lipschitz* classes and is compatible with several widely used techniques of linear approximation related to plant models. We can consider transformed problem instead of the original problem with respect to solvability and related questions.

## References

1. R. JUAREZ AND A.S. POZNYAK AND V. AZHMYAKOV AND UNDEFINED UNDEFINED. On applications of attractive ellipsoid method to dynamic processes governed by implicit differential equations. In Electrical engineering computing science and automatic control (cce), 2011 8th international conference on (p. 1-6). doi: 10.1109/ICEEE.2011.6106585.
2. R. JUAREZ AND V. AZHMYAKOV AND A. S. POZNYAK AND UNDEFINED UNDEFINED. Practical stability of control processes governed by semi-explicit daes. In Electrical engineering, computing science and automatic control (cce), 2012 9th international conference on (p. 1-6). doi: 10.1109/ICEEE.2012.6421214.
3. H. K. KHALIL. Nonlinear systems. Prentice-Hall, New Jersey , 2 (5), 5–1. 1996.
4. M. V. KUNKEL . Differential-algebraic equations. analysis and numerical solution. In Ems publishing house, zurich. 2006.
5. A. S. POZNYAK AND A. POLYAKOV AND V. AZHMYAKOV. Attractive ellipsoids in robust control. In (pp. 47–69). Cham: Springer International Publishing. Retrieved from [http://dx.doi.org/10.1007/978-3-319-09210-2\\_3](http://dx.doi.org/10.1007/978-3-319-09210-2_3) doi: 10.1007/978-3-319-09210-23. 2014.
6. R. JUAREZ AND V. AZHMYAKOV AND A. POZNYAK. Practical stability of control processes governed by semi-explicit daes. In Hindawi publishing corporation. mathematical problems in engineering. volume 2013, article id 6754408 (p. 1-7). doi: 10.1155/2013/6754408. 2013.